

Lecture 21

- Specializations cont.
- Template wizardry

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Template Template and Default Parameters

```
template <class T, template<class> class cont=std::vector>
struct Foo {
    void push(const T &val) { co.push_back(val); }
    T back() { return co.back(); }
    void pop(){ co.pop_back(); }
    bool empty() const { return co.empty(); }

private:
    cont<T> co;
};

Foo<int, std::stack> x;    // uses std::stack
Foo<char> y;              // uses std::vector
```

- Uninstantiated template class as template parameter
- In this example, template parameter `cont` gets instantiated with template type parameter `T`
- Purpose: adapt class to special needs, here: users can choose underlying LIFO data structure `stack<T>` or `vector<T>`

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Integer Template Parameters and Recursive Compile-Time Computations

```
template <int n> struct Fac // general case n! = n*(n-1)!
{
    enum { result = n * Fac<n-1>::result }; // constant
};

template <> struct Fac<0> // base case 0! = 1
{
    enum { result = 1 }; // constant
};

int main()
{
    // Fac<c>::result is now a compile-time constant!
    cout << Fac<5>::result << endl; // = 5! = 120
    cout << Fac<10>::result << endl; // = 10! = 3628800
    cout << Fac<0>::result << endl; // = 0! = 1
}
```

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Application: Type Traits (Compile-Time Type Reflection)

```
template <typename T> struct TypeTraits
{
    template <typename U> struct PointerTraits // general case
    {
        enum { result = false }; // no pointer
    };

    template <typename U> struct PointerTraits<U*> //spec. case
    {
        enum { result = true }; // is pointer
    };

    enum { is_pointer = PointerTraits<T>::result };
    // enum { isReference = ... };
    // enum { isConst = ... };
    // enum { isStdArith = ... }; // integral or floating point
    // enum { isStdFundamental = ... }; // => bit-wise copy OK
    // ...
};
```

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Compile-Time Assert

```
// generating compile-time errors depending on compile-time
// constant similar to assert
// idea: only provide template instantiation for true
// using false will generate compiler error msg.

template <bool x> struct ASSERTION_FAILURE; // incomplete type
template <> struct ASSERTION_FAILURE<true> // specialization
{ enum { value = 1 }; };

// fails if x is 0 or false
#define COMPILE_ASSERT(x) \
typedef char foo[ASSERTION_FAILURE<bool(x)>::value]

int main()
{
    // generates compile time error
    COMPILE_ASSERT(TypeTraits<char>::is_pointer);
    // OK
    COMPILE_ASSERT(TypeTraits<int*>::is_pointer);
}
```

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Using Metaprograms to Unroll Loops

```
// compute dot product of two vectors of size n
template <typename T> inline T dot(int n, T *a, T *b)
{
    T res = T(); // for numeric types equal to 0
    for (int i=0; i < n; ++i) res += a[i] * b[i];
    return res;
}

int main() {
    int a[3] = { 1, 2, 3 };
    int b[3] = { 4, 5, 6 };

    std::cout << dot(3, a, b) << endl; // 4+10+18=32
}
```

Problem: speed - unrolling the loop is faster! A smart compiler can figure that out when dim is a constant. I.e.:
 $\text{dot}(3, a, b) \Rightarrow a[0]*b[0] + a[1]*b[1] + a[2]*b[2]$

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Metaprogram Version

```
// recursive definition
template <int N, typename T> struct Dot {
    static T result(T *a, T *b) {
        return *a * *b + Dot<N-1, T>::result(a+1, b+1);
    }
};

// base case
template <typename T> struct Dot<1, T> {
    static T result(T *a, T *b) {
        return *a * *b;
    }
};

template <int N, typename T> inline T dot(T *a, T *b)
{
    return Dot<N, T>::result(a, b);
}
```

Call `dot<3>(a,b)` generates $a[0]*b[0] + a[1]*b[1] + a[2]*b[2]$
if compiler inlines one-line functions

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