

due date

(0)

Theorem:

$[A|\vec{b}]$ is row equivalent
to $[S|\vec{c}]$ in REF

(i) the system is inconsistent
if some row of $[S|\vec{c}]$ is
of the form

$$[0 \ 0 \ \dots \ 0 \ | \ c] \quad c \neq 0$$

(ii) If the number of pivots
in S is equal to the number
of variables then the system
has a unique solution.

(iii) If the number of pivots
is smaller than n
then the system has infinite
solutions

①

Finish example:

Reduced Row Echelon Form (RREF)

- (i) it is in row echelon form
- (ii) all leading entries are one.
- (iii) Columns with a leading 1, all other entries are 0.

Gauss-Jordan-Algorithm

- 1) Gaussian Algorithm $\rightarrow$ REF
- 2) Subtract multiple of bottom row of rows above to create zeros.

Theorem: For a given matrix A there is a unique matrix in RREF, which is row equivalent to A .

Independent?

Gauss

$$\begin{array}{ccc|ccc|ccc} 2 & 0 & 2 & 1 & 0 & 1 & 1 & 0 & 1 \\ 1 & 2 & 3 & 1 & 2 & 3 & 0 & 2 & 2 \\ 1 & 4 & 9 & 1 & 4 & 9 & 0 & 4 & 8 \\ 3 & 6 & 13 & 3 & 6 & 13 & 0 & 6 & 10 \end{array}$$

$$\begin{array}{ccc|ccc|ccc|ccc} 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 \\ 0 & 4 & 8 & 0 & 0 & 4 & 0 & 0 & 4 & 0 & 0 & 4 \\ 0 & 6 & 10 & 0 & 0 & 4 & 0 & 0 & 4 & 0 & 0 & 4 \end{array}$$

Gauss-Jordan

$$\begin{array}{l} R_2 - R_3 \\ R_1 - R_3 \end{array} \quad \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{array} \quad \text{RREF}$$

Df:

The rank of a matrix is the number of leading ones in its RREF

$$\rightarrow \text{rank}(A) = 3$$

Wednesday

(2)

Theorem:

Let $[A|\vec{b}]$ be a system of m linear eq. in n variables

(1) The system is consistent if and only if the rank of A and $[A|\vec{b}]$ are equal.

(2) If the system is consistent then the number of parameters in the standard solution is

$$\# \text{ of parameters} = n - \text{rank}(A)$$

$[A|\vec{b}]$ lin system m eq.
 n var.

then $[A|\vec{b}]$ is consistent for all $\vec{b}$ if $\text{rank}(A) = m$.

Homogeneous System

③

~~A~~ $\vec{b} = \vec{0}$

→ trivial solution

→ do not need to augment the matrix for finding the solution.

$$x_1 + x_2 + 2x_3 = 0$$

$$3x_1 + 3x_2 + 5x_3 = 0$$

$$\begin{bmatrix} 1 & 1 & 2 \\ 3 & 3 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 5 \\ 0 & 0 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{matrix} 0 \\ 0 \\ 0 \end{matrix} \rightarrow x_3 = 0$$

$$x_2 = t, \quad t \in \mathbb{R}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$x_1 = -t$$